

## RANDOM VARIABLES

**Definition** A **probability space**  $(S, \mathcal{E}, P)$  is composed of a sample space  $S$ , the algebra  $\mathcal{E}$  (see notes), and a probability function  $P : \mathcal{E} \rightarrow [0, 1]$  that satisfies Kolmogorov's axioms.

**Definition** A real-valued function  $X$  that maps one probability space  $(S, \mathcal{E})$  to another probability space  $(\Omega, \mathcal{F})$  is called a **random variable** (r.v.) if

$$X^{-1}(E) \in \mathcal{E} \text{ for all } E \in \mathcal{F}$$

That is, each event in the “new” algebra corresponds to (measurable) events in the original space. This ensures that  $X$  induces a consistent probability measure on the new space.

**Definition** Suppose r.v.  $X$  maps  $(S, \mathcal{E}, P) \rightarrow (\Omega, \mathcal{F}, P_X)$ . The probability function (measure)  $P_X$  is called the **probability distribution of  $X$**  and is given by

$$P_X(A) = P(\{s \in S : X(s) \in A\}) \text{ for all } A \in \mathcal{F}.$$

**NOTE:** By  $X$  being real-valued, we mean that  $\Omega \subseteq \mathbb{R}$  or  $\Omega \subseteq \mathbb{R}^n$ . In the latter case, we call  $X$  a **random vector**.

**Theorem:** The distribution of  $X$  is uniquely determined by the **cumulative distribution function** (cdf)  $F_X$  of  $X$ :

$$F_X(x) = P(X \leq x) = P((-\infty, x]).$$

### Properties of cdf

1.  $F$  is nondecreasing: If  $x_1 \leq x_2$ , then  $F(x_1) \leq F(x_2)$ ;
2.  $F$  is right - continuous: for any  $x$ ,  $\lim_{y \rightarrow x^+} F(y) = F(x)$ ;
3.  $\lim_{y \rightarrow \infty} F_Y(y) = 1$ ;
4.  $\lim_{y \rightarrow -\infty} F_Y(y) = 0$ .

**NOTE:** Here are two useful rules for computing probabilities:

1. For a sequence of *increasing* sets  $A_1 \subset A_2 \subset \dots$  the probability of their union is the limit of their probabilities, that is:  $P(\bigcup_{i=1}^{\infty} A_i) = \lim_{i \rightarrow \infty} P(A_i)$ .
2. For a sequence of *decreasing* sets  $A_1 \supset A_2 \supset \dots$  the probability of their intersection is the limit of their probabilities, that is:  $P(\bigcap_{i=1}^{\infty} A_i) = \lim_{i \rightarrow \infty} P(A_i)$ .

**Types of distributions:** There are three main types of distributions/random variables:

1. Discrete r.v.: CDF is a step function, has at most countable number of values.
2. Continuous r.v.: CDF is a continuous function, has intervals in the set of values.
3. Mixed r.v.: CDF is neither continuous nor step function.

## DISCRETE RANDOM VARIABLES (RVs)

**Definition.** Suppose a sample space  $S$  has finite or countable number of simple outcomes. Let  $p$  be a real valued function on  $S$  such that

1.  $0 \leq p(s) \leq 1$  for every element  $s$  of  $S$ ;
2.  $\sum_{s \in S} p(s) = 1$ ,

Then  $p$  is said to be a **discrete probability function**.

**NOTE:** For any event  $A$  defined on  $S$ :  $P(A) = \sum_{s \in A} p(s)$ .

**Definition.** A real valued function  $X : S \rightarrow \mathbb{R}$  is called a **random variable**.

**Definition.** A random variable with finite or countably many values is called a **discrete random variable**.

**Definition.** Any discrete random variable  $X$  is described by its **probability density function** (or probability mass function), denoted  $p_X(k)$ , which provides probabilities of all values of  $X$  as follows:

$$p_X(k) = P(s \in S : X(s) = k). \quad (1)$$

**NOTE:** For any  $k$  not in the range (set of values) of  $X$ :  $p_X(k) = 0$ .

**NOTE:** For any  $t \leq s$ ,  $P(t \leq X \leq s) = \sum_{k=t}^s P(X = k)$ .

**NOTATION:** For simplicity, we denote  $p_X(k) = P(X = k)$  thus suppressing the dependence on the sample space.

**Examples:**

1. Binomial random variable  $X$  with  $n$  trials and probability of success equal to  $p$ , i.e.,  $X \sim \text{binom}(n, p)$ .

$$p_X(k) = P(k \text{ successes in } n \text{ trials}) = \binom{n}{k} p^k (1-p)^{n-k}, \text{ for } k = 0, 1, 2, \dots, n. \quad (2)$$

2. Hypergeometric random variable  $X$ .

**Definition.** Let  $X$  a discrete random variable. For any real number  $t$ , the cumulative distribution function  $F$  of  $X$  at  $t$  is given by

$$F_X(t) = P(X \leq t) = P(s \in S : X(s) \leq t). \quad (3)$$

**Linear transformation:** Let  $X$  be a discrete random variable (rv). let  $Y=aX+b$ , where  $a$  and  $b$  are real constants. Then  $p_Y(y) = p_X(\frac{y-b}{a})$ .

## CONTINUOUS RANDOM VARIABLES (RVs)

Suppose a sample space  $\Omega$  is uncountable, e.g.,  $\Omega = [0, 1]$  or  $\Omega = \mathbb{R}$ . We can define a random variable  $X : (\Omega, \mathcal{E}) \rightarrow (S, \mathcal{B})$  where the new sample space  $S$  is a subset of  $\mathbb{R}$  and the algebra  $\mathcal{B}$  is the Borel sets (all unions, intersections and complements of the open and closed intervals in  $S$ ). The probability structure on such a space can be described using a special function,  $f$  called *probability density function* (pdf).

**Definition.** If sample space  $S \subseteq \mathbb{R}$  then we say  $P$  is a **continuous probability distribution** if there exists a function  $f(t)$  such that for any closed interval  $[a, b] \subset S$  we have that  $P([a, b]) = \int_a^b f(t)dt$ . It follows that  $P(A) = \int_A f(t)dt$  for all events  $A$ .

For a function  $f$  to be a pdf, it is necessary and sufficient that the following properties hold:

1.  $f(t) \geq 0$  for every  $t$ ;
2.  $\int_{-\infty}^{\infty} f(t)dt = 1$ .

**NOTE:** If  $P(A) = \int_A f(t)dt$  for all  $A$ , then  $P$  satisfies all the Kolmogorov probability axioms.

**Definition:** Any function  $Y$  that maps  $S$  (a subset of real numbers) into the real numbers is called a **continuous random variable**. The pdf of  $Y$  is a function  $f$  such that

$$P(a \leq Y \leq b) = \int_a^b f(t)dt.$$

For any event  $A$  defined on  $S$ :  $P(A) = \int_A f(t)dt$ .

**Theorem:** For any continuous random variable  $P(X = a) = 0$  for any real number  $a$ .

**Definition.** The cdf of a continuous random variable  $Y$  (with pdf  $f$ ) is  $F_Y(t)$ , given by

$$F_Y(y) = P(Y \leq y) = P(\{s \in S : Y(s) \leq y\}) = \int_{-\infty}^y f(t)dt \quad \text{for any real } y.$$

**Theorem.** If  $F_Y(t)$  is a cdf and  $f_Y(t)$  is a pdf of a continuous random variable  $Y$ , then

$$\frac{d}{dt}F_Y(t) = f_Y(t).$$

**Linear transformation:** Let  $X$  be a continuous random variable with pdf  $f$ . Let  $Y = aX + b$ , where  $a$  and  $b$  are real constants. Then the pdf of  $Y$  is:  $g_Y(y) = \frac{1}{|a|}f_X(\frac{y-b}{a})$ .

## EXPECTED VALUES OF RANDOM VARIABLES

To get an idea about the *central tendency* for a random variable, we compute its **expected value** (mean).

**Definition** Let  $X$  be a random variable.

1. If  $X$  is a discrete random variable with pdf  $p_X(k)$ , then the expected value of  $X$  is given by

$$E(X) = \mu = \mu_X = \sum_{\text{all } k} k \cdot p_X(k) = \sum_{\text{all } k} k \cdot P(X = k)$$

2. If  $X$  is a continuous random variable with pdf  $f$ , then

$$EX = \mu = \mu_X = \int_{-\infty}^{\infty} xf(x)dx.$$

3. If  $X$  is a mixed random variable with cdf  $F$ , then the expected value of  $X$  is given by

$$E(X) = \mu = \mu_X = \int_{-\infty}^{\infty} xF'(x)dx + \sum_{\text{all } k} k \cdot P(X = k),$$

where  $F'$  is the derivative of  $F$  where the derivative exists and  $k$ 's in the summation are the "discrete" values of  $X$ .

**NOTE:** For the expectation of a random variable to exist, we assume that all integrals and sums in the definition of the expectation above converge **absolutely**.

**Median** of a random variable - a value "dividing the distribution of  $X$  in halves. If  $X$  is a discrete random variable, then its median  $m$  is the point for which  $P(X < m) = P(X > m)$ . If there are two values  $m$  and  $m'$  such that  $P(X \leq m) = 0.5$  and  $P(X \geq m') = 0.5$ , the median is the average of  $m$  and  $m'$ ,  $(m + m')/2$ .

If  $X$  is a continuous random variable with pdf  $f$ , the median is the solution of the equation:

$$\int_{-\infty}^m f(x)dx = 0.5.$$